

READING GROUP: ASYMPTOTIC THEORY FOR STATIONARY PROCESSES (WU, 2011)

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Motivation (p.1)

- Finite-sample distributions can be impossible to derive in time series
- Usual tools like CLT and LLN are not tailored for time series
 - *Simple CLT relies on independence*
 - *Advance CLT imposes condition like α -mixing, which is hard to verify*
- Some asymptotic tools developed for linear time series before
 - *What if nonlinear?*
 - *Goal of this survey: general stationary process*

Stationary process

- Form: $X_i = H(\dots, \epsilon_{i-1}, \epsilon_i)$ where $\epsilon_i, i \in \mathbb{Z}$ are iid random variables
 - *Basis of Wu's 2005 PNAS paper*
 - *Avoid the use of strong mixing condition*
 - *Sometimes called nonlinear Wold representation*
- Casual interpretation: $\{\epsilon_t\}_{t \leq i}$ “cause” X_i
 - *X_i is independent of future innovation ϵ_j where $j > i$*
 - *Reason will be argued in next section*

REPRESENTATION THEORY

Section 2

Wold representation (1938) (p.2)

- Any weakly stationary process can be decomposed into
 - *A regular process (a moving average sum of white noises)*
 - *And a singular process (a linearly deterministic component)*
 - *Form: $X_t = \sum_{j=0}^{\infty} b_j \epsilon_{t-j} + \eta_t$*
- Also gives causal interpretation
 - *Stronger in the sense that it is linear*
- However not much insight for asymptotic distribution
 - *Joint distribution of white noises can be too complicated*

Rosenblatt transformation (1952)

- Any finite dimensional random vector can be expressed in distribution as functions of iid uniforms
 - *Based on quantile transformation: $X_n \stackrel{d}{=} (X_{n-1}, G_n(X_{n-1}, U_n))$*
- Not applicable on stationary ergodic process
 - *However suggest the usefulness of nonlinear Wold representation*
 - *Stationary: distribution of the random variables*
 - *Ergodic: statistical property can be deduced from sample paths*

Comparison

Representation	Form	Requirement	Asymptotic
Wold	$X_t = \sum_{j=0}^{\infty} b_j \epsilon_{t-j} + \eta_t$	Weakly stationary	No
Nonlinear Wold	$X_t = H(\dots, \epsilon_{t-1}, \epsilon_t)$	Strictly stationary	Yes

- Weakly stationary \Leftrightarrow Wold
- Strictly stationary \Leftrightarrow nonlinear Wold?
 - *Previous example suggest that nonlinear Wold can represent lots of process*
 - *Is there strictly stationary process that cannot be represented?*
 - Then we cannot use the asymptotic in this paper

DEPENDENCE MEASURES

Section 3

Physical dependence

- Physical dependence measure: $\delta_p(j) \stackrel{\text{def}}{=} \|X_j - X_j^*\|_p$ where $j \geq 0$
 - \mathcal{L}^p norm: $\|X\|_p \stackrel{\text{def}}{=} (E|X|^p)^{\frac{1}{p}}$
 - Shift process: $\mathcal{F}_i \stackrel{\text{def}}{=} (\dots, \epsilon_{i-1}, \epsilon_i)$
 - A bit like filtration of innovation
 - Coupled innovation: $(\epsilon'_i)_{i \in \mathbb{Z}}$ is iid copy of $(\epsilon_i)_{i \in \mathbb{Z}}$
 - Coupled X_j : $X_j^* = H(F_j^*)$ where $F_j^* = (\dots, \epsilon_{-1}, \epsilon'_0, \epsilon_1, \dots, \epsilon_{j-1}, \epsilon_j)$
 - Exchangeable: $(X_j, X_j^*) \stackrel{d}{=} (X_j^*, X_j)$
 - Idea: measure the causal effect of changing initial input ϵ_0 on output X_j
 - Rubin causality?

Predictive dependence

- Predictive dependence measure: $\omega_p(j) \stackrel{\text{def}}{=} \|g_j(\mathcal{F}_0) - g_j(\mathcal{F}_0^*)\|_p$ where $j \geq 0$
 - $g_j(\mathcal{F}_0) \stackrel{\text{def}}{=} E(X_j | \mathcal{F}_0)$
 - Nonlinear analogue of Kolmogorov's (1941, written in Russian) linear predictor
 - *Idea: measure the predictive effect of knowing initial input ϵ_0 on output X_j*
 - Granger causality?
- Lemma 1: $\theta_p(i) \leq \omega_p(i) \leq 2\theta_p(i)$
 - $\theta_p(i) \stackrel{\text{def}}{=} \|\mathcal{P}_0 X_i\|_p$
 - *Projection operator: $\mathcal{P}_j \stackrel{\text{def}}{=} E(\cdot | \mathcal{F}_j) - E(\cdot | \mathcal{F}_{j-1})$ where $j \in \mathbb{Z}$*
 - This naturally leads to martingale differences
 - *Interchangeable use of $\omega_p(i)$ and $\theta_p(i)$*

Projection operator

- Definition: $\mathcal{P}_j \stackrel{\text{def}}{=} E(\cdot | \mathcal{F}_j) - E(\cdot | \mathcal{F}_{j-1})$ where $j \in \mathbb{Z}$
 - Help decompose the predictive effect of knowing ϵ_j on X_i
 - $A = E(A) + \sum_{j=-\infty}^{\infty} \mathcal{P}_j A = \text{mean effect} + \text{contribution of } \epsilon_j \text{ on predicting } A$
 - $\mathcal{P}_i \mathcal{P}_j A = \begin{cases} \mathcal{P}_j A, & i = j \\ 0, & i \neq j \end{cases}$
 - result of tower property
 - $\mathcal{P}_j X_i = 0$ if $j > i$
 - future ϵ_j cannot cause X_i
 - $X_i = E(X_i) + \sum_{j=-\infty}^i \mathcal{P}_j X_i$

Stability (p.3)

- Stability: p -stable if $\Delta_p \stackrel{\text{def}}{=} \sum_{j=0}^{\infty} \delta_p(j) < \infty$
 - Interpretation: cumulative impact of ϵ_0 on $\{X_i\}_{i \geq 0}$ is finite
 - Short-range dependence condition
- Weak stability: weakly p -stable if $\Omega_p \stackrel{\text{def}}{=} \sum_{j=0}^{\infty} \omega_p(j) < \infty$
 - Interpretation: cumulative contribution of ϵ_0 in predicting $\{X_i\}_{i \geq 0}$ is finite
 - Weak stability with $p = 2$ guarantees an invariance principle for the partial sum process $S_n = \sum_{i=1}^n X_i$
 - Invariance principle: functional extension of CLT
- Why weak? (Wu, 2005): $\delta_p(j) \geq \omega_p(j)$ where $p \geq 1, j \geq 0$

Relationship

- Note that definitions in Wu (2005) are used instead

Name	Definition	Sum
Physical dependence $\delta_p(j)$	$\ X_j - X_j^*\ _p$	$\Delta_p < \infty \Rightarrow p$ -stable
Predictive dependence $\omega_p(j)$	$\ E(X_j \mathcal{F}_0) - E(X_j \mathcal{F}_0^*)\ _p$	$\Omega_p < \infty \Rightarrow$ weakly p -stable
Projection $\theta_p(j)$	$\ E(X_j \mathcal{F}_0) - E(X_j \mathcal{F}_{-1})\ _p$	$\Theta_p < \infty \Rightarrow$ weakly p -stable

- $\theta_p(j) \leq \omega_p(j) \leq \min[2\theta_p(j), \delta_p(j)]$
- $\Delta_p < \infty \Rightarrow \Theta_p \leq \Omega_p < \infty$ (stability implies weak stability)

Examples (p.4)

- Linear process: $X_t = \sum_{i=0}^{\infty} a_i \epsilon_{t-i}$
 - Existence can be confirmed with Kolmogorov's Three Series Theorem
 - $\delta_p(n) = \|a_n \epsilon_0 - a_n \epsilon'_0\|_p = |a_n| \times \|\epsilon_0 - \epsilon'_0\|_p = \omega_p(n)$
 - Stable if $\sum_{i=0}^{\infty} |a_i| < \infty$
- ARMA process: $X_t = \epsilon_t + \sum_{j=1}^p \phi_j X_{t-j} + \sum_{l=1}^q \theta_l \epsilon_{t-l}$
 - Special class of linear process
 - a_i is the coefficient of $\frac{1 + \sum_{l=1}^q \theta_l z^l}{1 - \sum_{j=1}^p \phi_j z^j}$

Volterra series

- Volterra expansion: functional extension of Taylor expansion
- Nonlinear Wold: $H(\dots, \epsilon_{n-1}, \epsilon_n) = \sum_{k=1}^{\infty} \sum_{u_1, \dots, u_k=0}^{\infty} g_k(u_1, \dots, u_k) \epsilon_{n-u_1} \dots \epsilon_{n-u_k}$
 - g_k are called Volterra kernel
 - Under the assumptions below, $X_n \in \mathcal{L}^2$ and exists
 - ϵ_t are iid with mean 0 and variance 1
 - $g_k(u_1, \dots, u_k)$ symmetric and = 0 if $u_i = u_j$ for some $1 \leq i < j \leq k$
 - $\sum_{k=1}^{\infty} \sum_{u_1, \dots, u_k=0}^{\infty} g_k^2(u_1, \dots, u_k) < \infty$
- Physical dependence: $\delta_p^2(n) = 2 \sum_{k=1}^{\infty} k \sum_{u_2, \dots, u_k=0}^{\infty} g_k^2(n, u_2, \dots, u_k)$
- Predictive dependence: $\omega_p^2(n) = 2 \sum_{k=1}^{\infty} k \sum_{u_2, \dots, u_k=n+1}^{\infty} g_k^2(n, u_2, \dots, u_k)$
 - Stable if $\sum_{i=1}^{\infty} \omega_p(i) < \infty$

NONLINEAR TIME SERIES

Section 4

Summary (p.4-7)

- Nonlinear $AR(p)$ model: $X_n = G(X_{n-1}, \dots, X_{n-p}; \epsilon_n)$ where $p \geq 1$ and $n \in \mathbb{Z}$
- Present sufficient condition for the above to have
 - *Stationary representation in form of nonlinear Wold*
 - *Geometric-moment contracting (GMC) property*
- Implication of GMC: $\delta_p(n) = O(r^n)$ for some $r \in (0,1)$
 - *Thus p -stable?*
- The rest are special cases of the above model
 - *E.g. Threshold AR, GARCH*

CENTRAL LIMIT THEORY

Section 5

Invariance principle (p.7-8)

- For simplicity, assume $E(X_i) = 0$ and $Cov(X_0, X_k) = \gamma_k$
- Traditional CLT: $\frac{S_n}{\sqrt{n}} \xrightarrow{d} N(0, \sigma^2)$ where $S_n = \sum_{i=1}^n X_i$
 - *Problems: autocorrelation, heteroskedasticity, no representation of σ^2*
- Invariance principle: $\left\{ \frac{S_{nu}}{\sqrt{n}}, 0 \leq u \leq 1 \right\} \xrightarrow{d} \{ \sigma W_u, 0 \leq u \leq 1 \}$
 - $S_t = S_{[t]} + (t - [t])X_{[t]+1}$ (extend S_n to a stochastic process)
 - W_u is a standard Brownian motion
 - *Entails CLT on S_n if holds*

Weak stability (p.8)

- If a time series is weakly p -stable, then $\Theta_p \stackrel{\text{def}}{=} \sum_{i=0}^{\infty} \theta_p(i) < \infty$
 - Weakly p -stable: $\Omega_p = \sum_{j=0}^{\infty} \omega_p(j) < \infty$
 - So this follows from lemma 1 that $\Theta_p \leq \Omega_p < \infty$
- Assume $E(X_i) = 0$ and $\Theta_p < \infty$, then we have
 - Moment inequality: $\|S_n\|_p \leq \begin{cases} (p-1)^{\frac{1}{2}} n^{\frac{1}{2}} \Theta_p, & p > 2 \\ (p-1)^{-1} n^{\frac{1}{p}} \Theta_p, & 1 < p \leq 2 \end{cases}$
 - Help to bound the order of remainder term related to moment of S_n
 - Example: $\hat{\theta}(\bar{X}) = \hat{\theta}(\mu) + [\hat{\theta}(\bar{X}) - \hat{\theta}(\mu)]$ (potentially easier to deal with $\hat{\theta}(\mu)$)
 - If $\Theta_2 < \infty$, $\left\{ \frac{S_{nu}}{\sqrt{n}}, 0 \leq u \leq 1 \right\} \xrightarrow{d} \{\sigma W_u, 0 \leq u \leq 1\}$
 - Where $\sigma^2 = \|\sum_{i=0}^{\infty} \mathcal{P}_0 X_i\|^2 = \sum_{k \in \mathbb{Z}} \gamma_k$
 - Martingale approximation: Volný (1993) Theorem B and Theorem 6

Martingale approximation

- Martingale property: X_t satisfying $E(X_t | \mathcal{F}_j) = X_j$ (best guess of future is present)
- Martingale difference sequence: $D_t = X_t - X_{t-1}$ satisfying $E(D_t | \mathcal{F}_{t-1}) = 0$
 - Projection $\mathcal{P}_{i-l}X_i$ is MDS by tower property since $\mathcal{F}_{i-l} \subset \mathcal{F}_{i-1}$
- Martingale approximation: $X_i = \sum_{l \in \mathbb{Z}} \mathcal{P}_{i-l}X_i$ ($E(X_i) = 0$ by assumption)
- Minkowski inequality: $\|v + w\|_p \leq \|v\|_p + \|w\|_p$
 - $\|S_n\|_p = \|\sum_{i=1}^n \sum_{l \in \mathbb{Z}} \mathcal{P}_{i-l}X_i\|_p \leq \sum_{l \in \mathbb{Z}} \|\sum_{i=1}^n \mathcal{P}_{i-l}X_i\|_p$
- Burkholder's inequality (1988): $c_p \left\| \sqrt{\sum_{i=1}^n D_i^2} \right\|_p \leq \|X_n\|_p \leq C_p \left\| \sqrt{\sum_{i=1}^n D_i^2} \right\|_p$
 - X_i is a martingale, $D_i = X_i - X_{i-1}$ is a MDS
 - $c_p < C_p$ are positive constants depends on p where $1 < p < \infty$
 - Idea: relate maximum of a martingale with its quadratic variation

Proof of moment inequality

- Apply Burkholder's inequality to $\|\sum_{i=1}^n \mathcal{P}_{i-l} X_i\|_p^p$
 - $\|\sum_{i=1}^n \mathcal{P}_{i-l} X_i\|_p^p \leq C'_p \|\sqrt{\sum_{i=1}^n (\mathcal{P}_{i-l} X_i)^2}\|_p^p = C'_p E |\sum_{i=1}^n (\mathcal{P}_{i-l} X_i)^2|^{\frac{p}{2}}$
 - $\leq C'_p \sum_{i=1}^n E |\mathcal{P}_{i-l} X_i|^p = C'_p \sum_{i=1}^n \|\mathcal{P}_{i-l} X_i\|_p^p$ (by power of sum inequality)
 - $= C'_p n \|\mathcal{P}_0 X_l\|_p^p$ (by \mathcal{L}^p stationarity)
- By summing $C_p n^{\frac{1}{p}} \|\mathcal{P}_0 X_l\|_p$, we have $\|S_n\|_p \leq (p-1)^{-1} n^{\frac{1}{p}} \Theta_p$, $1 < p \leq 2$
 - *The other case uses result of Rio (2009)*
 - *Tighter bound may have appeared in recent years but Wu's framework provides a uniform way to describe the condition*

Proof of invariance principle

- Doob's martingale inequality: to be discussed in the next paper

GAUSSIAN APPROXIMATION

Section 6

Strong invariance principle (p.8-9)

- Invariance principle does not specify rate of convergence
- Komlós–Major–Tusnády approximation (1975, 1976) for iid r.v.
 - Assume $X_i \in \mathcal{L}^p$ where $p > 2$, $E(X_i) = 0$
 - On a richer probability space, there exists $\{X'_i\}_{i \in \mathbb{Z}} \stackrel{d}{=} \{X_i\}_{i \in \mathbb{Z}}$ and $S'_n = \sum_{i=1}^n X'_i$
 - We have $\max_{0 \leq t \leq n} |S'_t - \sigma W_t| = o_{a.s.} \left(n^{\frac{1}{p}} \right)$
 - Where $\sigma = \|X_i\|$
 - Further assume $E(e^{t|X_1|}) < \infty$, we have $\max_{0 \leq t \leq n} |S'_t - \sigma W_t| = o_{a.s.}(\log n)$
 - A bit like MGF exists

KMT approximation under dependence

- Theorem (Wu, 2007):

- Assume $X_i \in \mathcal{L}^p$ where $2 < p \leq 4$ has nonlinear Wold representation
- Assume $E(X_i) = 0$ and $\sum_{i=1}^{\infty} [\delta_p(i) + i\omega_p(i)] < \infty$
 - $\sum_{i=1}^{\infty} i\delta_p(i) < \infty$ is sufficient
- Then on a richer probability space, there exists $\{X'_i\}_{i \geq 0} \stackrel{d}{=} \{X_i\}_{i \geq 0}$
- We have $\max_{0 \leq t \leq n} |S'_t - \sigma W_t| = o_{a.s.} \left[n^{\frac{1}{p}} (\log n)^{\frac{1}{2} + \frac{1}{p}} (\log \log n)^{\frac{2}{p}} \right]$
 - Where $\sigma = \|\sum_{i=0}^{\infty} \mathcal{P}_0 X_i\|$

- Theorem (Berkes, Liu & Wu, 2014):

- Under some other mild assumptions, we have $S'_n - \sigma W_n = o_{a.s.} \left(n^{\frac{1}{p}} \right)$
- Read the AoP paper if you are interested

SAMPLE COVARIANCE FUNCTION

Section 7

CLT with bounded k

- Sample autocovariance: $\hat{\gamma}_k \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=k+1}^n (X_i - \bar{X})(X_{i-k} - \bar{X})$ where $0 \leq k < n$
 - If $\mu = 0$, then $\hat{\gamma}_k = \frac{1}{n} \sum_{i=k+1}^n X_i X_{i-k}$
- Assume $E(X_i) = 0, X_i \in \mathcal{L}^p$ where $2 < p \leq 4$ and $\Delta_p < \infty$
 - Let $Y_i = (X_i, \dots, X_{i-k})^T$ and $\Gamma_k = (\gamma_0, \dots, \gamma_k)^T$ where $k \in \mathbb{N}$ is fixed, we have
 - Moment inequality: $\left\| \hat{\gamma}_k - \left(1 - \frac{k}{n}\right) \gamma_k \right\|_{\frac{p}{2}} \leq \frac{3p-3}{n} \Theta_p^2 + \frac{4n^{\frac{p}{2}-1}}{p-2} \|X_1\|_p \Delta_p$
 - If $X_i \in \mathcal{L}^4$ and $\Delta_4 < \infty$, $\sqrt{n}(\hat{\gamma}_0 - \gamma_0, \dots, \hat{\gamma}_k - \gamma_k) \xrightarrow{d} N[0, E(D_0 D_0^T)]$
 - Where $D_0 = \sum_{i=0}^{\infty} \mathcal{P}_0(X_i Y_i) \in \mathcal{L}^2$

Proof of bounded k (p.10)

- Jensen's inequality: $\phi[E(X)] \leq E[\phi(X)]$ where $\phi(\cdot)$ is convex
 - Every \mathcal{L}^p norm is convex by Minkowski inequality
- Product identity: $ab - \hat{a}\hat{b} \equiv a(b - \hat{b}) + \hat{b}(a - \hat{a})$
 - As we usually have good knowledge of $a - \hat{a}$ and $b - \hat{b}$
- Cauchy-Schwarz inequality: $|\sum_{i=1}^n a_i b_i| \leq \sqrt{(\sum_{i=1}^n a_i)^2 (\sum_{i=1}^n b_i)^2}$
 - Probabilistic version: $|E(XY)| \leq \sqrt{E(X^2)E(Y^2)}$
- Cramér-Wold device: $\vec{X}^{(n)} \xrightarrow{d} \vec{X} \Leftrightarrow \sum_{i=1}^k t_i X_i^{(n)} \xrightarrow{d} \sum_{i=1}^k t_i X_i \quad \forall \vec{t} \in \mathbb{R}^k$
 - Help establish multivariate convergence using univariate result

CLT with unbounded k

- Asymptotic distribution does not depend on the speed of $k_n \rightarrow \infty$
- Assume $E(X_i) = 0, k_n \rightarrow \infty$ and $\Delta_p < \infty$
 - Let $Z_i = (X_i, \dots, X_{i-h+1})^T$ where $h \in \mathbb{N}$ is fixed, we have
 - $\frac{1}{\sqrt{n}} \sum_{i=1}^n [X_i Z_{i-k_n} - E(X_{k_n} Z_0)] \xrightarrow{d} N(0, \Sigma_h)$
 - Where Σ_h has entries $\sigma_{ab} = \sum_{j \in \mathbb{Z}} \gamma_{j+a} \gamma_{j+b} = \sigma_{0, a-b}$ where $1 \leq a, b \leq h$
 - If $\frac{k_n}{n} \rightarrow 0, \sqrt{n} \left[(\hat{Y}_{k_n}, \dots, \hat{Y}_{k_n-h+1})^T - (\gamma_{k_n}, \dots, \gamma_{k_n-h+1})^T \right] \xrightarrow{d} N(0, \Sigma_h)$
- The above results come from Wu (2008) for short-range dependence
 - Can be extended to long-range linear process

Estimation problem of γ_k

- $\hat{\gamma}_k$ is not a good estimator of γ_k when k is large
 - Example: $k \rightarrow \infty$ with $\frac{k}{n} \rightarrow 0$ satisfies $\sqrt{n}\gamma_k \rightarrow 0$
 - MSE of $\hat{\gamma}_k$: $E[(\hat{\gamma}_k - \gamma_k)^2] \sim \frac{\sigma_{00}}{n}$
 - MSE of $\tilde{\gamma}_k = 0$: $E[(\tilde{\gamma}_k - \gamma_k)^2] = o\left(\frac{1}{n}\right) \ll O\left(\frac{1}{n}\right)$
 - Little o: $f(x) = o(g(x)) \Leftrightarrow \lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = 0$
- Shrinkage estimate $\hat{\gamma}_k \mathbb{I}_{|\hat{\gamma}_k| \geq c_n}$ with carefully chosen $c_n \rightarrow 0$ can reduce MSE
 - Similar to Stein's phenomenon (discussed last semester)
 - Details to be discussed in next section

ESTIMATION OF COVARIANCE MATRIX

Section 8

Convergence problem of $\hat{\Sigma}_n$ (p.11)

- Operator norm: $\rho(A) \stackrel{\text{def}}{=} \max_{x \in \mathbb{R}^n: |x|=1} |Ax|$
 - $|x| \stackrel{\text{def}}{=} \sqrt{\sum_{i=1}^n x_i^2}$
 - Hence $\rho^2(A)$ is the largest eigenvalue of $A^T A$
- Previous entry-wise convergence result does not imply matrix convergence of $\hat{\Sigma}_n$
 - Inconsistency is due to previous estimation problem
 - Conjecture (Wu & Pourahmadi, 2009): $\rho(\hat{\Sigma}_n - \Sigma_n) \xrightarrow{d} \text{Gumbel}(0,1)$
 - With proper centering and scaling
 - Gumbel distribution is usually used in extreme value theory

Truncation technique

- Banded covariance matrix estimator: $\hat{\Sigma}_{n,l_n} = (\hat{\gamma}_{i-j} \mathbb{I}_{|i-j| \leq l_n})_{1 \leq i, j \leq n}$
 - Under suitable conditions on banding parameter l_n , $\hat{\Sigma}_{n,l_n}$ is consistent
 - However $\hat{\Sigma}_{n,l_n}$ may not be non-negative definite
- Tapered version: $\tilde{\Sigma}_{n,l_n} = \left(\hat{\gamma}_{i-j} w\left(\frac{|i-j|}{l_n}\right) \right)_{1 \leq i, j \leq n} = \hat{\Sigma}_n \star W_n$
 - \star is the element-wise product
 - $w(\cdot)$ is a lag window function (aka kernel) satisfying some conditions
 - Such that W_n is non-negative definite
 - Example (Bartlett kernel/triangular window): $w_B(u) = \max(0, 1 - |u|)$
- Schur Product Theorem: $A \star B$ is non-negative definite if A, B are non-negative definite

Result of $\hat{\Sigma}_n$

- Theorem (Wu & Pourahmadi, 2009):
 - Assume X_i has nonlinear Wold representation and $\Theta_2 < \infty$
 - If $\sigma = \|\sum_{i=0}^{\infty} \mathcal{P}_0 X_i\| > 0$, then $\rho(\hat{\Sigma}_n - \Sigma_n) \xrightarrow{p} 0$
 - i.e. inconsistency when long-run variance is non-zero
- Theorem (Xiao & Wu, 2010):
 - Assume X_i has nonlinear Wold representation and $E(X_i) = 0$
 - Assume $X_i \in \mathcal{L}^p$ where $p > 2$ and $\sum_{i=j}^{\infty} \delta_p(i) = o\left(\frac{1}{\log j}\right)$ as $j \rightarrow \infty$
 - Assume $\min_{\vartheta} f(\vartheta) > 0$
 - f is the spectral density function which will be discussed in next section
 - Then $\exists c > 0$ s.t. $\lim_{n \rightarrow \infty} P\left[c^{-1} \log n \leq \rho(\hat{\Sigma}_n - \Sigma_n) \leq c \log n\right] = 1$
 - i.e. $\rho(\hat{\Sigma}_n - \Sigma_n) = o(\log n)$ as $n \rightarrow \infty$
- These two theorems implies $\hat{\Sigma}_n$ usually does not converge

Result of $\tilde{\Sigma}_{n,l_n}$

- Upper bound: assume $E(X_i) = 0$ and $\Delta_p < \infty$ for $2 < p \leq 4$
 - Let $b_n = \sum_{k=1}^l \left| 1 - w\left(\frac{k}{l}\right) + \frac{k}{n} w\left(\frac{k}{l}\right) \right| |\gamma_k| + \sum_{j=l+1}^n |\gamma_j|$
 - Then $\|\rho(\tilde{\Sigma}_{n,l} - \Sigma_n)\|_q \leq 2b_n + (l+1) \frac{4\|X_1\|_p \Delta_p}{n^{1-\frac{1}{q}(p-2)}}$ where $q = \frac{p}{2}, 0 \leq l < n$
 - Note that this bound is non-asymptotic
 - Hence if $l = l_n \rightarrow \infty$ and $\frac{l_n}{n^{1-\frac{1}{q}}} \rightarrow 0$, $\|\rho(\tilde{\Sigma}_{n,l} - \Sigma_n)\|_q \rightarrow 0$
- Theorem (Xiao & Wu, 2010):
 - Assume $X_i \in \mathcal{L}^p$ where $p > 4$ and $\Theta_p(m) = O(m^{-\alpha})$ where $\alpha > 0$
 - Let $l_n \asymp n^\lambda$ where $\lambda \in (0,1)$ satisfy $\lambda < \frac{p\alpha}{2}$ and $(1 - 2\alpha)\lambda < 1 - \frac{4}{p}$
 - Then $\rho(\tilde{\Sigma}_{n,l} - \Sigma_n) = O(b_n) + O_{\mathbb{P}} \left[n^{-\frac{1}{2}} (l_n \log l_n)^{\frac{1}{2}} \right]$
 - Adding additional assumptions gives a lower bound

Special cases (p.12)

- Assume $p = 4$ and $\gamma_k = O(\rho^k)$ for some $0 < \rho < 1$
- Rectangular window: $w(k) = 1$ for $|k| \leq l$
 - Choose $l = l_n = \left\lfloor \frac{\log n}{-2 \log \rho} \right\rfloor$, then $\|\rho(\tilde{\Sigma}_{n,l} - \Sigma_n)\| = O\left(n^{-\frac{1}{2}} \log n\right)$
 - Almost optimal but may not be non-negative definite
- Bartlett window: $w(k) = 1 - \frac{|k|}{l}$ for $|k| \leq l$
 - Choose $l \asymp n^{\frac{1}{4}}$, then
 - $\|\rho(\tilde{\Sigma}_{n,l} - \Sigma_n)\| = O(1) \sum_{k=1}^l [1 - w(k)] |\gamma_k| + O\left(\ln^{-\frac{1}{2}} + \rho^l\right) = O\left(n^{-\frac{1}{4}}\right)$
- Parzen window: $1 - w_p(u) = O(u^2)$
 - Choose $l \asymp n^{\frac{1}{6}}$, then
 - $\|\rho(\tilde{\Sigma}_{n,l} - \Sigma_n)\| = O\left(l^{-2} + \ln^{-\frac{1}{2}} + \rho^l\right) = O\left(n^{-\frac{1}{3}}\right)$

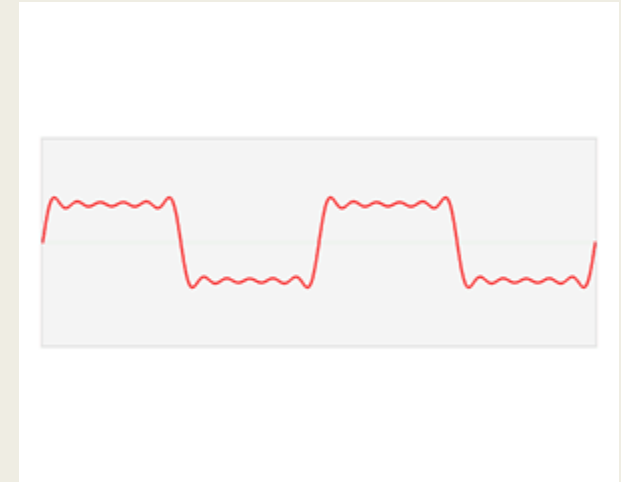
Application

- The upper bound can be applied to Wiener-Kolmogorov prediction
 - *Since γ_k can only be estimated with finite sample in practice*
 - *Probably referring to Wiener filter*
 - *Kalman filter is nonstationary extension of Wiener filter*
 - More popular in practice
- Help establish asymptotic theory of estimates of coefficients in
 - *Wold decomposition theorem*
 - *Discrete Wiener-Hopf equations*
 - A method to solve systems of integral equations

PERIODOGRAMS

Section 9

Frequency domain



- Time domain: changes of a signal with respect to time
- Frequency domain: changes of a signal with respect to frequency
 - *How much of a signal lies within each given band over a range of frequencies*
- Why frequency domain?
 - *Simplify the mathematical analysis*
 - *Give an intuitive understanding of the qualitative behavior of the system*
 - E.g. periodicity, power

Tools (p.12-13)

- Periodogram: $I_n(\phi) \stackrel{\text{def}}{=} \frac{|S_n(\phi)|^2}{n} \quad \forall \phi \in \mathbb{R}$
 - Discrete Fourier transform (DFT): $S_n(\phi) = \sum_{t=1}^n x_t e^{it\phi}$ where $i = \sqrt{-1}$
- Spectral distribution function: right-continuous, non-decreasing F that satisfy
 - $\gamma_k = \int_0^{2\pi} e^{ik\phi} dF(\phi)$ and is bounded on $[0, 2\pi]$
- Spectral density function: $f = F'$ if F is absolutely continuous
- Theorem (Peligrad & Wu, 2010): for regular nonlinear Wold process,
 - If $\sum_{k \in \mathbb{Z}} |\gamma_k| < \infty$, then $f(\phi) = \frac{1}{2\pi} \sum_{k \in \mathbb{Z}} \gamma_k e^{ik\phi} = \frac{1}{2\pi} \sum_{k \in \mathbb{Z}} \gamma_k \cos(k\phi)$
 - Euler's formula: $e^{i\phi} = \cos \phi + i \sin \phi$
 - Continuity property: if $u_p = \sum_{k=1}^{\infty} k^p |\gamma_k| < \infty$, then $f \in \mathcal{C}^p(\mathbb{R})$
 - Larger p such that $u_p < \infty$ means weaker serial dependence

Central limit problem of $S_n(\phi)$

- Assume X_t is second order stationary, $E(X_t) = 0$ and $\sum_{k \in \mathbb{Z}} |\gamma_k| < \infty$
 - Then $E[I_n(\phi)] = \sum_{k=1-n}^{n-1} \left(1 - \frac{|k|}{n}\right) \gamma_k \cos(k\phi) \rightarrow 2\pi f(\phi)$ as $n \rightarrow \infty$
 - Hence $\frac{|S_n(\phi)|^2}{2\pi n}$ is asymptotically unbiased for $f(\phi)$
 - Note that $S_n(\phi)$ comes from discrete transform but $f(\phi)$ comes from continuous
 - However it is inconsistent by the following theorem
- Theorem: assume $E(X_t^2) < \infty$
 - For almost all $\vartheta \in \mathbb{R}$ (Lebesgue), we have $\begin{pmatrix} \Re \\ \Im \end{pmatrix} \frac{S_n(\vartheta)}{\sqrt{n}} \xrightarrow{d} N[0, \pi f(\vartheta) Id_2]$
 - Consequently, $\frac{I_n(\vartheta)}{2\pi f(\vartheta)} \xrightarrow{d} Exp(1)$
 - Proposition: this holds $\forall \vartheta \in (0, 2\pi)$ if $\sum_{i=0}^{\infty} \|\mathcal{P}_0 X_i - \mathcal{P}_0 X_{i+1}\| < \infty$
 - A sufficient condition is $\Theta_p < \infty$
 - For almost all pairs (ϑ, φ) (Lebesgue), $\frac{S_n(\vartheta)}{\sqrt{n}} \perp \frac{S_n(\varphi)}{\sqrt{n}}$ asymptotically

Fast Fourier transform

- Discrete Fourier transform: $O(n^2)$ time complexity to obtain $S_n(\vartheta_j), j = 1, \dots, n$
- Fast Fourier transform: $O(n \log_2 n)$ time complexity to obtain same estimate
 - *A size- N ($N = N_1 N_2$) DFT can be expressed as two DFTs with size N_1, N_2*
 - *This is possible by complex root of unity (aka twiddle factors)*
 - *Cooley-Tukey algorithm*
- Faster Fourier transform?
 - *Lower bound on time complexity of FFT is an open problem*
 - *Some results under sparsity (Hassanieh et. al., 2012)*

Central limit problem of $S_n(\vartheta_j)$

- Theorem: assume X_i is nonlinear Wold, $\Theta_p < \infty$ and $\min_{\vartheta} f(\vartheta) > 0$,
 - Let $q \in \mathbb{N}$, $m = \lfloor \frac{n-1}{2} \rfloor$ and $Y_k \stackrel{iid}{\sim} N(0,1)$ for $1 \leq k \leq 2q$
 - Then $\left\{ \frac{S_n(\vartheta_{l_j})}{\sqrt{n\pi f(\vartheta_{l_j})}}, 1 \leq j \leq q \right\} \xrightarrow{d} \{Y_{2j-1} + iY_{2j}, 1 \leq j \leq q\}$
 - Where $1 \leq l_1 < \dots < l_q \leq m$ may depend on n
 - Consequently, $\left\{ \frac{I_n(\vartheta_{l_j})}{f(\vartheta_{l_j})}, 1 \leq j \leq q \right\} \xrightarrow{d} \{E_j, 1 \leq j \leq q\}$ where $E_j \stackrel{iid}{\sim} \text{Exp}(1)$
 - The remaining part discuss the maximum error of approximation (?)
 - Continuous mapping theorem: $X_n \xrightarrow{d} X \Rightarrow g(X_n) \xrightarrow{d} g(X)$ if $g(\cdot)$ is continuous
 - This is only the part used. Check standard reference for full theorem
 - Theorem (Lin & Liu, 2009) states convergence to standard Gumbel

ESTIMATION OF SPECTRAL DENSITIES

Section 10

Estimation problem of $f(\theta)$ (p.14)

- Inconsistency of $I_n(\vartheta)$ (though unbiased) proved in last section
- Lag window estimator: $f_n(\theta) = \frac{1}{2\pi} \sum_{k=1-n}^{n-1} K\left(\frac{k}{B_n}\right) \hat{Y}_k e^{ik\theta}$ where
 - Bandwidth B_n satisfies $B_n \rightarrow \infty$ and $\frac{B_n}{n} \rightarrow 0$
 - Window K is symmetric, bounded, continuous at 0 and $K(0) = 1$
 - This estimator is consistent but its limiting distribution is highly nontrivial
- Theorem (Liu & Wu, 2010): assume $E(X_t) = 0, E(X_t^4) < \infty$ and $\Delta_4 < \infty$
 - Let $B_n \rightarrow \infty$ and $B_n = o(n)$ as $n \rightarrow \infty$
 - Assume K is symmetric, bounded, $\lim_{u \rightarrow 0} K(u) = K(0) = 1$
 - Assume $\kappa \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} K^2(u) du < \infty$ and K is continuous at all but finite points
 - Assume $\sup_{0 < w \leq 1} \sum_{j \geq \frac{c}{w}} K^2(jw) \rightarrow 0$ as $c \rightarrow \infty$
 - Then $\sqrt{\frac{n}{B_n}} \{f_n(\theta) - E[f_n(\theta)]\} \xrightarrow{d} N\left[0, \left(1 + \mathbb{I}_{\frac{\theta}{\pi} \in \mathbb{Z}}\right) f^2(\theta) \kappa\right]$ for $0 \leq \theta < 2\pi$

Long-run variance

- Long-run variance: $2\pi f(0) = \frac{2\pi}{2\pi} \sum_{k \in \mathbb{Z}} \gamma_k \cos(0) = \sum_{k \in \mathbb{Z}} \gamma_k = \sigma^2$
 - *First equality is due to theorem in Peligrad & Wu (2010) (slide p.41)*
 - *Last equality is due to probabilistic representation of σ^2 (slide p.20)*
- Put $\theta = 0$ in the previous CLT, we have $\sqrt{\frac{n}{B_n}} \{f_n(0) - f(0)\} \xrightarrow{d} N[0, 2f^2(0)\kappa]$
 - *If the bandwidth $b_n = B_n^{-1}$ satisfy*
 - $2\pi\{E[f_n(0)] - f(0)\} = \sum_{k=1-n}^{n-1} K(kb_n) \left(1 - \frac{|k|}{n}\right) \gamma_k - \sum_{k \in \mathbb{Z}} \gamma_k = o\left[(nb_n)^{-\frac{1}{2}}\right]$
- Log transformation can stabilize the variance (ease CI but may lose good property)
 - $\sqrt{\frac{n}{B_n}} [\log f_n(0) - \log f(0)] \xrightarrow{d} N(0, 2^2)$

Recursive estimation

- Lag window estimator is non-recursive as bandwidth depends on n
 - *When bandwidth changes, all blocks need to be updated (time complexity)*
 - *If all blocks need to be updated, we need store all data (space complexity)*
- Recursive estimation is possible by letting bandwidth depends on i
 - *When bandwidth changes, only the new block need to be updated*
 - *If bandwidth is increasing in a block, we only need the new data*
- Xiao and Wu (2010) provides algorithm for spectral density
- Wu (2009), Chan and Yau (2017) provides algorithms for long-run variance

KERNEL ESTIMATION

Section 11

Kernel regression

- Model: $Y_i = G(X_i, \eta_i), X_i = (\dots, \epsilon_{i-1}, \epsilon_i)$
 - Important example: the autoregressive model $X_{i+1} = R(X_i, \epsilon_{i+1})$
- Nadaraya-Watson estimator of $g(x_0) = E(Y_n | X_n = x_0)$: $g_n(x_0) = \frac{T_n(x_0)}{f_n(x_0)}$
 - $T_n(x) = \frac{1}{n} \sum_{t=1}^n Y_t K_{b_n}(x - X_t)$ where $K_{b_n}(x) = \frac{1}{b_n} K\left(\frac{x}{b_n}\right)$
 - Kernel K is symmetric, bounded on \mathbb{R} , has bounded support and $\int_{\mathbb{R}} K(u) du = 1$
 - Bandwidth $b_n \rightarrow 0$ and $nb_n \rightarrow \infty$
 - $f_n(x_0) = \frac{1}{n} \sum_{t=1}^n K_{b_n}(x_0 - X_t)$
 - Rosenblatt's (1956) kernel density estimate

CLT for $g_n(x_0)$

- l -step ahead conditional densities: $F_l(X_{i+l} \leq x | \mathcal{F}_i)$, $f_l(x | \mathcal{F}_i) = \frac{d}{dx} F_l(x | \mathcal{F}_i)$
- Theorem (Wu, 2005; Wu, Huang & Huang, 2010)
 - Assume $\exists c_0 < \infty$ s. t. $\sup_{x \in \mathbb{R}} f_1(x | \mathcal{F}_i) \leq c_0$ a. s. and $\sum_{i=1}^{\infty} \sup_x \|\mathcal{P}_0 f_1(x | \mathcal{F}_i)\| < \infty$
 - Assume $b_n \rightarrow 0$, $nb_n \rightarrow \infty$ and let $\kappa = \int_{\mathbb{R}} K^2(u) du$
 - Then $\sqrt{nb_n} \{f_n(x_0) - E[f_n(x_0)]\} \xrightarrow{d} N[0, f(x_0)\kappa]$
 - Let $V_p(x) = E|G(x, \eta_n)|^p$ and $\sigma^2(x) = V_2(x) - g^2(x)$
 - If $f(x_0) > 0$, $V_2, g \in \mathcal{C}(\mathbb{R})$ and $V_p(x)$ is bounded on a neighborhood of x_0
 - Then $\sqrt{nb_n} \left\{ g_n(x_0) - \frac{E[T_n(x_0)]}{E[f_n(x_0)]} \right\} \xrightarrow{d} N \left[0, \frac{\sigma^2(x_0)\kappa}{f(x_0)} \right]$
 - Note that $E \left[\frac{T_n(x_0)}{f_n(x_0)} \right]$ does not necessary equal to $\frac{E[T_n(x_0)]}{E[f_n(x_0)]}$
 - This implies they are probably independent

Maximum deviation

- Maximum deviation: $\Lambda_n \stackrel{\text{def}}{=} \sup_{l \leq x \leq u} \sqrt{\frac{nb}{\kappa f(x)}} |f_n(x) - E[f_n(x)]|$
- Theorem (Liu & Wu, 2010)
 - Assume $X_n = a_0 \epsilon_n + g(\dots, \epsilon_{i-2}, \epsilon_{i-1}) \in \mathcal{L}^p$ for some $p > 0$ where $a_0 \neq 0$
 - Assume pdf f_ϵ of ϵ_1 is positive and $\sup_{x \in \mathbb{R}} [f_\epsilon(x) + |f'_\epsilon(x)| + |f''_\epsilon(x)|] < \infty$
 - Assume $\exists 0 < \delta_2 \leq \delta_1 < 1$ such that $n^{-\delta_1} = o(b_n)$ and $b_n = o(n^{-\delta_2})$
 - Let $p' = \min(p, 2)$ and $\Theta_n = \sum_{i=0}^n \delta_{p'}(i)^{\frac{p'}{2}}$
 - Assume $\Psi_{n,p'} = o(n^{-\gamma})$ for some $\gamma > \frac{\delta_1}{1-\delta_1}$
 - Assume $\sum_{k=-n}^{\infty} (\Theta_{n+k} - \Theta_k)^2 = o(b_n^{-1} n \log n)$
 - Let the kernel $K \in \mathcal{C}^1[-1,1]$ with $K(\pm 1) = 0, l = 0$ and $u = 1$
 - Then $P \left[(2 \log b^{-1})^{-\frac{1}{2}} \Lambda_n - 2 \log b^{-1} - \frac{1}{2} \log K_3 \leq z \right] \rightarrow e^{-2e^{-z}} \forall z \in \mathbb{R}$
 - Where $K_3 = \frac{\int_{-1}^1 [K'(t)]^2 dt}{4\pi^2 \int_{-1}^1 K^2(t) dt}$

U-STATISTICS

Section 12

U -statistic

- Weighted U -statistic: $U_n = \sum_{1 \leq i, j \leq n} w_{i-j} K(X_i, X_j)$
 - Where $w_i = w_{-i}$ are weights and K is symmetric measurable function
 - Predictive dependence: $\theta_{i,j} = \|\mathcal{P}_0 K(X_i, X_j)\|$
- Theorem (Hsing and Wu, 2004)
 - Assume $\sum_{k=0}^{\infty} \sum_{i=0}^{\infty} |w_k| \theta_{i,i-k} < \infty$ (summable weights)
 - Then $\exists \sigma^2 < \infty$ such that $\frac{1}{\sqrt{n}} [U_n - E(U_n)] \xrightarrow{d} N(0, \sigma^2)$
 - Let $W_n(i) = \sum_{j=1}^n w_{i-j}$ and $W_n = \sqrt{\frac{1}{n} \sum_{i=1}^n W_n^2(i)}$
 - Assume $\sum_{i=1}^{\infty} |w_i| = \infty$, $\sum_{k=0}^n (n-k) w_k^2 = o(nW_n^2)$, $\liminf_{n \rightarrow \infty} \frac{W_n}{\sum_{i=0}^{\infty} |w_i|} > 0$
 - Assume $\sum_{l=0}^{\infty} \sup_{j \in \mathbb{Z}} \|K(X_0, X_j) - K(\tilde{X}_0, \tilde{X}_j)\| < \infty$
 - Where $\tilde{X}_j = E(X_j | \epsilon_{j-l}, \dots, \epsilon_j)$
 - Then $\exists \sigma_U^2 < \infty$ such that $\frac{1}{W_n \sqrt{n}} [U_n - E(U_n)] \xrightarrow{d} N(0, \sigma_U^2)$